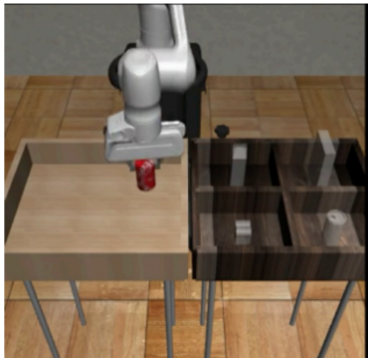
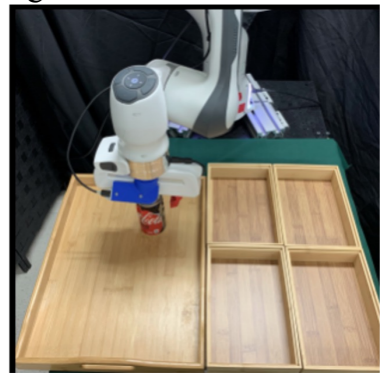


Training Environment (simulation)



Testing Environment (real robot)



Multimodal Sensory Input

